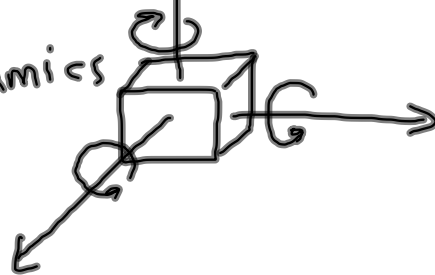


Physics - rigid body dynamics

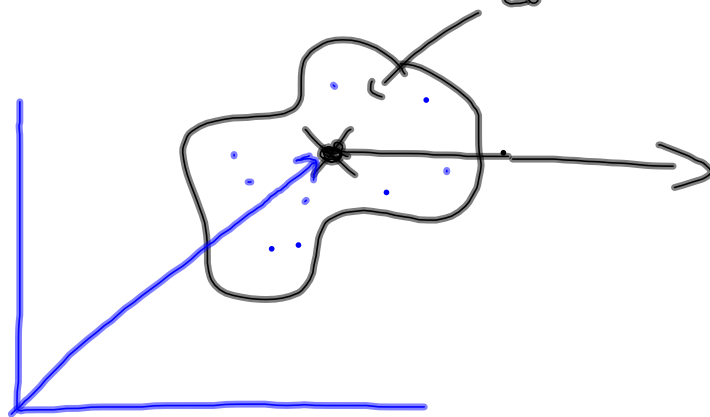
Ch 12.4...

Angular Dynamics
(rotation)



Linear Dynamics
(movement)

Linear Dynamics



$r(t)$ position over time m
 $v(t)$ velocity m/s
 $a(t)$ accel. m/s^2

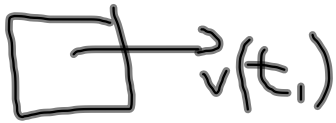
Force $F(t) = m \cdot a(t)$ $kg \cdot m/s^2$ (Newtons)

$$F_{net}(t) = \sum_{i=1}^N F_i(t)$$

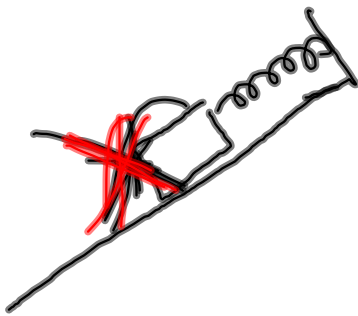
momentum

$$p(t) = m \cdot v(t)$$

$$F(t) = \frac{dp(t)}{dt}$$

$r(t_1)$  Δt : time since last frame

$$r(t_2) = r(t_1) + v(t_1)\Delta t$$



Forces
gravity
spring
friction
explosion

$$F_{\text{net}} = m \cdot a(t)$$

$$a(t_2) = \frac{F_{\text{net}}}{m}$$

$$v(t_2) = v(t_1) + a(t_1)\Delta t$$

Explicit
Euler